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APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
10/581,791	06/06/2006	Mark Lawrence Williams	1033963-000025	5493
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			2462	
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Please find below and/or attached an Office communication concerning this application or proceeding.

The time period for reply, if any, is set in the attached communication.

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	Application No.	Applicant(s)
	10/581,791	WILLIAMS, MARK LAWRENCE
Office Action Summary	Examiner	Art Unit
	LEON ANDREWS	2462
The MAILING DATE of this communication a Period for Reply	appears on the cover sheet wit	h the correspondence address
A SHORTENED STATUTORY PERIOD FOR REF WHICHEVER IS LONGER, FROM THE MAILING - Extensions of time may be available under the provisions of 37 CFR after SIX (6) MONTHS from the mailing date of this communication. - If NO period for reply is specified above, the maximum statutory perion - Failure to reply within the set or extended period for reply will, by stat Any reply received by the Office later than three months after the ma earned patent term adjustment. See 37 CFR 1.704(b).	DATE OF THIS COMMUNIC 1.136(a). In no event, however, may a re od will apply and will expire SIX (6) MONT tute, cause the application to become ABA	ATION. ply be timely filed THS from the mailing date of this communication. ANDONED (35 U.S.C. § 133).
Status		
1) ■ Responsive to communication(s) filed on 19 2a) ■ This action is FINAL . 2b) ■ TI 3) ■ Since this application is in condition for allow closed in accordance with the practice under	his action is non-final. vance except for formal matte	-
Disposition of Claims		
4) ☐ Claim(s) <u>1-9</u> is/are pending in the application 4a) Of the above claim(s) is/are withd 5) ☐ Claim(s) is/are allowed. 6) ☐ Claim(s) <u>1-9</u> is/are rejected. 7) ☐ Claim(s) is/are objected to. 8) ☐ Claim(s) are subject to restriction and	rawn from consideration.	
Application Papers		
9) The specification is objected to by the Exami 10) The drawing(s) filed on is/are: a) a Applicant may not request that any objection to the Replacement drawing sheet(s) including the correct 11) The oath or declaration is objected to by the	ccepted or b) objected to be ne drawing(s) be held in abeyand ection is required if the drawing(s	ce. See 37 CFR 1.85(a). s) is objected to. See 37 CFR 1.121(d).
Priority under 35 U.S.C. § 119		
12) Acknowledgment is made of a claim for foreign a) All b) Some * c) None of: 1. Certified copies of the priority documed 2. Certified copies of the priority documed 3. Copies of the certified copies of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the International Bured * See the attached detailed Office action for a life of the priority documed application from the Internation for a life of the	ents have been received. ents have been received in Apriority documents have been reau (PCT Rule 17.2(a)).	oplication No received in this National Stage
Attachment(s) 1) Motice of References Cited (PTO-892)	4) ☐ Interview Su	ummary (PTO-413)
2) Notice of Draftsperson's Patent Drawing Review (PTO-948) 3) Information Disclosure Statement(s) (PTO/SB/08) Paper No(s)/Mail Date	Paper No(s)	/Mail Date formal Patent Application

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DETAILED ACTION

Reopening of Prosecution after Pre Appeal Request

- 1. Applicant's arguments, filed May 19, 2010 with respect to rejected claims 1, 3-10 and 12-22 have been fully considered and are persuasive. The Final Office Action of May 27, 2009 has been withdrawn. However, upon further consideration, a new ground(s) of rejection is made. See rejection below for full details.
- 2. Claims 1-9 are rejected under 35 U.S.C. 103(a) as being unpatentable by Mookerjee et al. (Patent No.: US 7,180,443 B1) in view of Eid et al. (Patent No.: US 6,502,042 B1) and Rui et al. (aPub. No.: US 2004/0220769 A1).

Regarding Claims 1 and 5, Mookerjee et al. discloses a network (Fig. 1. 10, tracking system includes a radar antenna that transmits and receive signals, column 1, lines 18-22) and a method (method comprises the steps of initializing a filter with an initial state machine and matrices, columns 5 and 6, lines 66-67 and 1-2 respectively) for estimating a system state (state estimation processing measurements of system, column 1, lines 7-8), the network comprising a plurality of nodes (Fig. 1, aircraft 12 and radar antenna 14a; linear and nonlinear systems, column 11, line 63), each node having means for receiving and sending information (Fig. 1, radar antenna 14a and aircraft 12 transmit and receive signals, column 1, lines 1-23) and means for processing information (Fig. 1, measurements applied to processing arrangement 16, column 1, lines 28-29), and each node being connected to selected other nodes (Fig. 1, aircraft 12 and radar antenna 14a) of the network, each node including:

particle filter means (Fig. 3, 322, compute filter; systems to which filters apply, column 11, lines 63-64) for maintaining a set of particles (systems with parameters as inputs, column 11, lines 65-66; systems such as aircraft, space station, etc, column 12, lines 17-23) and associated weights (weighting the measurement of the state of the system, column 6, lines 28-29), which represent an estimate of the system state, and means for updating the set (Fig. 3, 326, updating state estimate; state estimate is updated with filter matrix weighting the measurement of the state of the system, column 6, lines 27-29; weighting the states with new measurement at each update of the filter, column 9, lines 22-23) when new information is available,

means (Fig. 3, initialize state estimate; estimating the state of the system, column 4, lines 29-30; state estimation of a system, column 5, lies 63-64) for representing the estimating system state as a mixture of Gaussian distributions (Gaussian distribution approximates the maximum accelerations produced by the parameters and represented by a statistical model by weighting the states with a measurement at the filter, column 9, lines 9-22), and means for communicating said mixture to neighbouring nodes (Fig. 1, radar antenna 14a transmits and receives signals, column 1, lines 21-22),

said means for updating, being responsive to receiving said mixture from a neighbouring node (Fig. 3, 324, input measurement from sensor), for updating its estimate of the system state (Fig. 3, 326, updating state estimate).

Mookerjee et al. fails to specifically disclose plurality of nodes.

But, the Eid et al. discloses network with a plurality of nodes where each of the node is connected to each of the (other) nodes in the layer, column 13, lines 23-27.

Therefore, it would have been obvious to a person of ordinary skill in the art at the time the invention was made to use Eid et al.'s limitation because this would have allowed the input to the (other) nodes in the layer could the weight of the input nodes and vice versa with the input to the output node(s) is the weight of the (other) nodes in the layer, column 13, lines 31-41.

The combination of Mookerjee et al. and Eid et al. fails to specifically disclose estimated state as a mixture of Gaussian distribution.

But, the Rui et al. discloses estimated states are in the form of Gaussian distribution, paragraph [0012], page 2, lines 1-5.

Therefore, it would have been obvious to a person of ordinary skill in the art at the time the invention was made to use Rui et al.'s limitation because this would have allowed the state estimates to be in the form of Gaussian distribution, paragraph [0012], page 2, lines 4-5.

Regarding Claims 2 and 7, Mookerjee et al. discloses a network and a method, wherein said channel filter is operative to compute new weights (Fig. 3, 322, compute filter gains; filter weighting the measurement of the state of the system to generate current (new) system estimate, column 6, lines 28-31) for each particle in a resampling operation (state estimate updated (resampling) with the filter, column 6, lines 27-28), the new weights (weighting the states with new measurement at each update of the filter, column 9, lines 22-23) comprising said mixture of Gaussian distributions (Gaussian distribution in an equivalent statistical and filter models airplane tracking, column 9, lines 9-15) communicated to the node, divided by said mixture of Gaussian distributions (Gaussian distribution in an equivalent statistical and filter models airplane tracking, weighting the states with new measurement with each successive update of the filter, column 9,

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lines 9-23) representing the existing particle set at said node.

Regarding Claims 3 and 8, Mookerjee et al. discloses a network and a method, wherein said means for communicating is operative to transmit each Gaussian distribution (Gaussian distribution in the filter model defined to have covariance using this filter model, whereby the covariance is achievable by weighting the states with new measurement with each successive update of the filter, column 9, lines 12-23) of said mixture as signals representing the mean and covariance (Fig. 3, 326, update state estimate, covariance) of the distribution.

Regarding Claims 4 and 6, Mookerjee et al. discloses a network and a method, wherein a communication port (port of the radar system 14, column 1, lines 25-26) of each node includes a channel filter (filter for fusion of data from multiple sensors, column 3, lines 59-61; systems to which filters apply, column 11, lines 63-64).

Regarding Claim 9, Mookerjee et al. discloses a network as claimed in claim 5, wherein each node is a sensor (Fig. 3, 324, measurement from sensor; filter for fusion of data from multiple sensors, column 3, lines 59-61) for tracking aircraft (Fig. 1, tacking system tracks an aircraft target 12 using a radar system (sensor), column 1, lines 18-20).

Response to Arguments

3. Applicant's arguments filed May 19, 2010 have been considered. But, in view of the new grounds of rejections resulting from the use of new prior art in the prosecution of the claims,

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the arguments are moot.

Conclusion

4. Any inquiry concerning this communication or earlier communications from the examiner

should be directed to LEON ANDREWS whose telephone number is (571)270-1801. The examiner

can normally be reached on Monday through Friday 7:30 AM to 5:00 PM EST.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor,

Rao S. Seema can be reached on (571) 272-3174. The fax phone number for the organization where

this application or proceeding is assigned is 571-273-8300.

Information regarding the status of an application may be obtained from the Patent

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LA/la

November 20. 2010

/Kevin C. Harper/

Primary Examiner, Art Unit 2462